

TITLE OF THE INVENTION

HEART-SOUND DETECTING APPARATUS

BACKGROUND OF THE INVENTION

Field of the Invention

[0001] The present invention relates to a heart-sound detecting apparatus and particularly to such an apparatus which detects a heart sound by extracting or determining, from a physical signal containing a heart-sound component, the heart-sound component.

Related Art Statement

[0002] Heart sounds are detected to make diagnosis of heart disease. In addition, heart sounds may be detected to determine, in combination with a pulse wave, a pulse-wave propagation velocity at which the pulse wave propagates through a living subject. In addition, since pulse-wave propagation velocity reflects arteriosclerosis which, in turn, directly relates to hypertension, it is desirable to measure, at home, the velocity as part of a daily medical check.

[0003] In general, heart sounds are detected using a heart-sound microphone which is usually directly worn on skin of a prescribed portion of the chest, e.g., right above the heart. A heart-sound signal provided by the heart-sound microphone worn on the chest has a great signal-to-noise (S/N) ratio. Thus, the heart-sound signal which is filtered by a standardized filter can directly be used to determine a reference point for making diagnosis or determining pulse-wave propagation velocity.

[0004] However, when the heart-sound microphone is used to detect heart sounds, the subject needs to take off the cloth and thereby expose the chest. Thus, it is considerably cumbersome to detect heart sounds using the heart-sound microphone. In particular, when pulse-wave propagation velocity is measured, at home, as part of a daily medical check, it is desirable to detect heart sounds in an easier manner.

[0005] In this background, it has been proposed to provide a heart-sound detecting apparatus which detects a heart sound at a position distant from the chest of a living subject, based on the fact that the heart sound is transmitted from the heart to that position. This apparatus is disclosed in U.S. Patent Application claiming priority from Japanese Patent Application No. 2001-030879. This apparatus includes a pressure-pulse-wave sensor which is worn on an upper arm of a subject and extracts a heart-sound component from a pressure-pulse-wave signal supplied from the sensor.

[0006] However, the magnitude of the heart-sound component contained in the pressure-pulse-wave signal or physical signal detected from the upper arm distant from the chest, is weak, and the magnitude of the other signal components, such as physical sounds occurring to the upper arm, external noise, or artifact, is strong. Therefore, in many cases, the signal filtered by the conventional, standardized filter may not be used to determine one or more reference points which are needed to make diagnosis or determine pulse-wave propagation velocity.

SUMMARY OF THE INVENTION

[0007] It is therefore an object of the present invention to provide a heart-sound detecting apparatus which can accurately determine a heart-sound component which is contained in a physical signal, even if the magnitude of the heart-sound component may be weak relative to the magnitude of the physical signal as a whole.

[0008] The Inventors have intensively studied about how to achieve the above-indicated object, and obtained the following finding: Usually, a heart-sound signal supplied by a heart-sound microphone is filtered by a filter having a considerably large frequency range, because there are great differences among respective heart-sound signals obtained from individual subjects. That is, the respective heart sounds of individual subjects may have largely different frequency ranges and/or waveforms. Hence, the Inventors have found that if a heart-sound frequency range and/or a heart-sound waveform of each individual subject are/is determined, in advance, as heart-sound characteristic information, a heart-sound component can be accurately determined, based on the heart-sound characteristic information, from a physical signal actually detected from the each subject, even if the magnitude of the heart-sound component may be weak relative to that of the physical signal as a whole. The present invention has been developed based on this finding.

[0009] The above object has been achieved by the present invention. According to a first feature of the present invention, there is provided an apparatus for detecting a heart sound of a

living subject, comprising a memory device which stores heart-sound characteristic information which is characteristic of a heart sound of the subject; a heart-sound sensor which is adapted to be worn on a body portion of the subject that is distant from a chest of the subject and which detects, from the body portion, a physical signal containing a heart-sound component and supplies the physical signal; and a heart-sound determining means for determining, based on the heart-sound characteristic information stored in the memory device, the heart-sound component contained in the physical signal.

[0010] According to this feature, the memory device stores heart-sound characteristic information which is characteristic of a heart sound of the living subject, and the heart-sound determining means determines, based on the heart-sound characteristic information characteristic of the heart sound, the heart-sound component contained in the physical signal supplied by the heart-sound sensor. Therefore, even if the magnitude of the heart-sound component may be weak relative to that of the physical signal as a whole, the present apparatus can accurately determine the heart-sound component.

[0011] According to a second feature of the present invention, the heart-sound characteristic information comprises a heart-sound frequency range consisting of a plurality of frequencies which are predetermined by subjecting, to a frequency analysis, the heart sound detected in advance from the chest of the subject, and the heart-sound determining means extracts, from the physical signal, the heart-sound component

having the plurality of frequencies of the heart-sound frequency range.

[0012] According to this feature, the memory device stores the heart-sound frequency range which is predetermined based on the heart sound detected in advance from the chest of the subject and which is characteristic of the subject, and the heart-sound determining means extracts, from the physical signal supplied by the heart-sound sensor, the heart-sound component having the frequencies of the heart-sound frequency range. Thus, even if the magnitude of the heart-sound component may be weak relative to that of the physical signal as a whole, the present apparatus can accurately extract the heart-sound component.

[0013] According to a third feature of the present invention, the heart-sound characteristic information comprises a first portion of the heart sound detected in advance from the chest of the subject, the first portion being detected during a predetermined time interval, and the heart-sound determining means determines, as the heart-sound component, a second portion of the physical signal supplied by the heart-sound sensor, the second portion having a length corresponding to the predetermined time interval and having a waveform best approximating a waveform of the first portion of the heart sound.

[0014] According to this feature, the memory device stores, as the heart-sound characteristic information characteristic of the subject, a portion of the heart sound which is detected in advance from the chest of the subject and which has a great

signal-to-noise ratio. Since the heart-sound determining means determines, as the heart-sound component, a portion of the physical signal detected by the heart-sound sensor that has a length corresponding to the predetermined time interval and has a waveform best approximating a waveform of the portion of the heart-sound signal stored in the memory device, the present apparatus can accurately determine the heart-sound component from the physical signal even if the magnitude of the heart-sound component contained in the physical signal may be weak.

[0015] According to a fourth feature of the present invention, the heart-sound characteristic information comprises a first portion of the heart sound detected in advance from the chest of the subject, the first portion having a plurality of frequencies of a heart-sound frequency range which is predetermined based on a frequency-time analyzed signal of the heart sound, and being detected during a predetermined time interval, and the heart-sound determining means determines, as the heart-sound component, a second portion of the physical signal supplied by the heart-sound sensor, the second portion having the plurality of frequencies of the heart-sound frequency range, having a length corresponding to the predetermined time interval, and having a waveform best approximating a waveform of the first portion of the heart sound.

[0016] According to this feature, the memory device stores a portion of the heart sound, detected in advance from the chest of the subject, that has the frequencies of a heart-sound frequency range which is predetermined based on a frequency-

time analyzed signal of the heart sound, and is detected during a predetermined time interval, and the heart-sound determining means determines, as the heart-sound component, a portion of the physical signal, supplied by the heart-sound sensor, that has the frequencies of the heart-sound frequency range, has a length corresponding to the predetermined time interval, and has a waveform best approximating a waveform of the stored portion of the heart sound. Thus, the present apparatus can accurately determine the heart-sound component from the physical signal.

BRIEF DESCRIPTION OF THE DRAWINGS

[0017] The above and optional objects, features, and advantages of the present invention will be better understood by reading the following detailed description of the preferred embodiments of the invention when considered in conjunction with the accompanying drawings, in which:

Fig. 1 is a diagrammatic view showing a construction of a pulse-wave-propagation-velocity measuring apparatus functioning as a heart-sound detecting apparatus, to which the present invention is applied;

Fig. 2 is a development view of an inflatable cuff of the apparatus of Fig. 1;

Fig. 3 is a plan view of a pressure-pulse-wave sensor of the apparatus of Fig. 1;

Fig. 4 is a block diagram for explaining essential functions of a control device of the apparatus of Fig. 1, including the functions of detecting a heart sound and determining, based

on the detected heart sound, a pulse-wave propagation velocity;

Fig. 5 is a graph showing a wavelet function;

Fig. 6A is a graph showing a wavelet function $\Psi((t - b)/a)$ which approximates a portion of a certain function $g(t)$;

Fig. 6B is a graph showing the product of the wavelet function $\Psi((t - b)/a)$ and the function $g(t)$;

Fig. 7A is a graph showing the wavelet function $\Psi((t - b)/a)$ which does not approximate a portion of a certain function $h(t)$;

Fig. 7B is a graph showing the product of the wavelet function $\Psi((t - b)/a)$ and the function $h(t)$;

Fig. 8A is a graph showing a heart-sound signal SH which is supplied from a heart-sound microphone 74 of the apparatus of Fig. 1;

Fig. 8B is a graph showing a contour map which is obtained by subjecting the heart-sound signal SH shown in Fig. 8A, to a time-frequency analysis, i.e., a wavelet transform;

Fig. 9 is a cross-section view for explaining a state in which the cuff is wound around an upper arm of a living subject;

Fig. 10 is a graph showing a relationship between individual pressure-sensing semiconductor elements and respective amplitudes of respective pressure-pulse-wave signals SM generated by the individual pressure-sensing elements;

Fig. 11 is a graph showing a pressure pulse wave BAP from which noise has been extracted by a noise removing means;

Fig. 12 is a flow chart representing a control program according to which the control device of Fig. 4 operates for obtaining heart-sound-characteristic information; and

Fig. 13 is a flow chart representing a control program according to which the control device of Fig. 4 operates for determining a pulse-wave propagation velocity.

DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

[0018] Hereinafter, there will be described a preferred embodiment of the present invention in detail by reference to the accompanying drawings. Fig. 1 shows a diagrammatic view showing a construction of a pulse-wave-propagation-velocity measuring apparatus 10 functioning as a heart-sound detecting apparatus, to which the present invention is applied. The present apparatus 10 also functions as a blood-pressure measuring apparatus.

[0019] In Fig. 1, reference numeral 12 designates an inflatable cuff which is adapted to be wound around a right upper arm 14 of a patient. Fig. 2 is a development view of the cuff 12. As shown in Fig. 2, the cuff 12 includes a belt-like cover bag 16 which is formed of a non-stretchable and considerably rigid cloth and has substantially the same length as that of a common inflatable cuff which is used to measure a blood pressure of an upper arm of a patient. However, a width of the cuff 12 is longer than that of the common cuff by a length corresponding to a width of a small cuff 20, described below.

[0020] In the cover bag 16, there are provided a large cuff

18 and the small cuff 20 each of which has substantially the same length (e.g., 24 cm) as that of a circumferential length of the upper arm 14 and is formed of rubber. The large cuff 18 has substantially the same width as that of a rubber bag employed in the common cuff. The width of the small cuff 20 is smaller than that of the large cuff 18 and is, for example, 2 cm. The large cuff 18 and the small cuff 20 are provided such that respective one long sides thereof are adjacent to each other. In a state in which the cuff 12 is wound around the upper arm 14, the small cuff 20 is positioned at a distal-side end of the cuff 12. The large cuff 18 and the small cuff 20 are connected to respective pipings 22, 24 for supplying pressurized air thereto.

[0021] A flexible support plate 26 which has substantially the same width as that of the small cuff 20 is fixed to an inner surface of the cuff 12 that contacts the upper arm 14 when the cuff 12 is wound around the same 14. More specifically described, the support plate 26 is fixed to a portion of the inner surface of the cuff 12 that corresponds to the small cuff 20, so that when the cuff 12 is wound around the upper arm 14, the support plate 26 is pressed by the small cuff 20. The support plate 26 supports four pressure-pulse-wave sensors 28 such that the four sensors 28 are arranged along a straight line in a lengthwise direction of the plate 26. Between each pair of adjacent sensors 28, there is provided a considerably small space of 0.9 mm length. Each pressure-pulse-wave sensor 28 produces a pressure-pulse-wave signal SM containing not only a brachial-artery-pulse-wave component but also a heart-sound component. Thus, each

pressure-pulse-wave sensor 28 also functions as a heart-sound sensor.

[0022] Fig. 3 is a plan view of one of the four pressure-pulse-wave sensors 28. The sensor 28 has a press surface 30 which is defined by a semiconductor chip such as monocrystalline silicon and has a length of about 13 mm in a lengthwise direction of the cuff 12 (i.e., in a left-right direction in Fig. 3). In the press surface 30, there are provided a number of semiconductor-based pressure sensing elements (or pressure detecting elements) 32 at a regular interval of distance along a straight line in the lengthwise direction of the cuff 12. In the present embodiment, each pressure-pulse-wave sensor 28 has fifteen pressure sensing elements 32 which are arranged at a regular spacing interval of 0.2 mm.

[0023] Back to Fig. 1, the large cuff 18 is connected to a pressure sensor 34, a deflation control valve 36, and an air pump 38 via the piping 22. The deflation control valve 36 is selectively placed in a pressure-supply position in which the control valve 36 permits a pressurized air to be supplied from the air pump 38 to the large cuff 18, a slow-deflation position in which the control valve 18 permits the pressurized air to be slowly discharged from the large cuff 18, and a quick-deflation position in which the control valve 36 permits the pressurized air to be quickly discharged from the large cuff 18.

[0024] The pressure sensor 34 detects an air pressure PK_1 in the large cuff 18, and supplies a first pressure signal SP_1 representing the detected pressure PK_1 , to each of a low-pass

filter 40 and a high-pass filter 42 via an amplifier, not shown. The low-pass filter 40 extracts, from the pressure signal SP_1 , a static-pressure component contained in the signal SP_1 , i.e., a cuff-pressure signal SK representing the pressing pressure of the large cuff 18. The cuff-pressure signal SK is supplied to a control device 46 via an A/D (analog-to-digital) converter 44. The high-pass filter 42 extracts, from the pressure signal SP_1 , an alternating component having frequencies not lower than 0.8 Hz, and supplies the thus extracted alternating-component signal to a low-pass filter 48 via an amplifier, not shown. The low-pass filter 48 extracts, from the alternating-component signal supplied from the high-pass filter 42, an alternating component having frequencies not higher than 10.8 Hz. This alternating-component signal provides a cuff-pulse-wave signal SW representing the alternating component of the pressure signal SP_1 . The cuff-pulse-wave signal SW is supplied to the control device 46 via an A/D converter 50.

[0025] The small cuff 20 is connected to a pressure sensor 52, a pressure control valve 54, and an air pump 56 via the piping 24. The pressure sensor 52 detects an air pressure PK_2 in the small cuff 20, and supplies a second pressure signal SP_2 representing the detected pressure PK_2 , to the control device 46 via an A/D converter 50. The pressure control valve 54 changes the pressure of the pressurized air supplied from the air pump 56, and supplies the pressurized air having the thus changed pressure to the small cuff 20.

[0026] A multiplexer 60 sequentially supplies, according to

a switch signal SC supplied from the control device 46, the respective pressure-pulse-wave signals SM supplied from the sixty pressure sensing elements 32 of the four pressure-pulse-wave sensors 28, each signal SM for a prescribed time duration, to an amplifier 62. An EPROM (erasable programmable ROM) 64 stores, for the sixty pressure sensing elements 32, respective correction signals for eliminating respective individual sensitivity differences among the pressure sensing elements 32, and sequentially supplies, according to the switch signal SC supplied from the control device 46, i.e., in synchronism with the respective switching operations of the multiplexer 60, the respective correction signals, to a D/A (digital-to-analog) converter 68, in such a manner that the respective correction signals sequentially correspond to the respective pressure sensing elements 32 supplying the respective pressure-pulse-wave signals SM being currently dealt with by the multiplexer 60.

[0027] Each of the sixty pressure-pulse-wave signals SM that have been amplified by the amplifier 62, and a corresponding one of the sixty correction signals that have been converted to respective analog signals by the D/A converter 68 are supplied to an amplifier 70. Thus, the sixty corrected pressure-pulse-wave signals SM supplied to the amplifier 70 have a uniform sensitivity. Each of the sixty corrected pressure-pulse-wave signals SM is supplied to an I/O (input-and-output) port of the control device 46 via an A/D converter 72.

[0028] A heart-sound microphone 74 is adapted to be worn

on a prescribed position on a skin of a chest of the living subject, detects heart sounds of the subject, and supplies a heart-sound signal SH representing the detected heart sounds, to the control device 46 via an A/D converter 76. A memory device 78 which may be provided by a RAM, a magnetic disc device (HDD), or a removable medium (MO, DVD, etc.) stores heart-sound-characteristic information, such as a heart-sound frequency range RF or a reference waveform, described later.

[0029] The control device 46 is provided by a so-called microcomputer including a CPU (central processing unit) 80, a ROM (read only memory) 82, and a RAM (random access memory) 84. The CPU 80 processes signals according to the control programs pre-stored in the ROM 82 by utilizing the temporary-storage function of the RAM 84, and controls the deflation control valve 36 and the air pump 38 to carry out a blood-measure measurement, controls the pressure control valve 54 and the air pump 56 to detect a pressure pulse wave, determines a blood-pressure value BP, extracts a heart sound, determines a pulse-wave-propagation velocity PWV, and controls a display device 86 to display the thus determined blood-pressure value BP and pulse-wave-propagation velocity PWV.

[0030] Fig. 4 is a block diagram for explaining essential functions of the control device 46 of the pulse-wave-propagation-velocity measuring apparatus 10, in particular, the functions of detecting heart sounds and determining, based on the detected heart sounds, a pulse-wave-propagation velocity.

[0031] A heart-sound-characteristic-information obtaining

means 90 includes a time-frequency analyzing means 92, a heart-sound-frequency range determining means 94, and a reference-waveform determining means 96. The time-frequency analyzing means 92 analyzes, with respect to time and frequency, the heart-sound signal SH supplied from the heart-sound microphone 74 (i.e., carries out a time-and-frequency analysis of the signal SH). The time-frequency analyzing means 92 simultaneously analyzes, with respect to both time and frequency, the heart-sound signal SH. Thus, the time-frequency analyzing means 92 provides a time-wise change of the frequency-analyzed magnitude values of the signal SH, by utilizing, e.g., a wavelet transform, or a fast Fourier transform (FFT) as applied to each of prescribed time intervals.

[0032] The wavelet transform will be described below. A wavelet function, $\Psi(t)$, shown in Fig. 5, is modified to a function, $\Psi((t - b)/a)$, of a translate parameter, b , to translate a waveform represented by the function $\Psi(t)$, along a time axis, t , and a scale parameter, a , to expand or contract the width of the waveform represented by the function $\Psi(t)$, along the time axis t . The wavelet transform is defined as a function of the parameters a , b that is obtained by integrating, with respect to the time t , the product of the thus modified wavelet function $\Psi((t - b)/a)$ and a function $f(t)$ representing the heart-sound signal SH. That is, the wavelet transform is defined by the following expression (1) pre-stored in the ROM 8:

$$W(b, 1/a) = \int_{-\infty}^{\infty} \frac{1}{\sqrt{|a|}} \Psi\left(\frac{t-b}{a}\right) f(t) dt \quad \dots (1)$$

[0033] Since the waveform represented by the modified wavelet function $\Psi((t - b)/a)$ has a width scaled by the parameter a along the time axis t , a parameter, $1/a$, indicates frequency; and since the waveform represented by the wavelet function $\Psi((t - b)/a)$ is translated by the parameter b along the time axis t , the parameter b indicates time.

[0034] Figs. 6A and 6B, and Fig. 7A and 7B are graphs for explaining what is meant by the wavelet transform defined by the above expression (1). Fig. 6A shows that a wavelet function $\Psi((t - b)/a)$ in which appropriate parameters a , b have been selected substantially approximates a portion of a certain function $g(t)$; and Fig. 7A shows that the wavelet function $\Psi((t - b)/a)$ does not approximate any portions of a certain function $h(t)$. Fig. 6B shows the product of the wavelet function $\Psi((t - b)/a)$ and the function $g(t)$ shown in Fig. 6A; and Fig. 7B shows the product of the wavelet function $\Psi((t - b)/a)$ and the function $h(t)$ shown in Fig. 7A. In the case, shown in Fig. 6A, in which the wavelet function $\Psi((t - b)/a)$ substantially approximates a portion of the function $g(t)$, the plus or minus sign of the product of the wavelet function $\Psi((t - b)/a)$ and the function $g(t)$ does not change as the time t elapses. Therefore, a great value is obtained by integrating the product function. On the other hand, in the case, shown in Fig. 7A, in which the wavelet function $\Psi((t - b)/a)$ does not approximate any portions of the function $h(t)$, the plus

and minus sign of the product of the wavelet function $\Psi((t - b)/a)$ and the function $h(t)$ frequently changes from plus to minus and from minus to plus as the time t elapses. Therefore, only a small value is obtained by integrating the product function. Thus, the above-indicated expression (1) provides a great value when the parameters a , b are appropriately selected so that the wavelet function $\Psi((t - b)/a)$ approximates a portion of the function $f(t)$ representing the heart-sound signal SH; and the expression (1) provides a small value when the wavelet function $\Psi((t - b)/a)$ does not approximate any portions of the function $f(t)$.

[0035] In the above-indicated expression (1), the scale parameter a corresponding to the frequency f and the translate parameter b corresponding to the time t are gradually changed and, each time at least one of the two parameters a , b is changed, an integral value is obtained from the wavelet transform, i.e., expression (1). Fig. 8A shows a waveform of the heart-sound signal SH supplied from the heart-sound microphone 74; and Fig. 8B shows a three-dimensional graph (i.e., a contour map) that is obtained by analyzing the waveform of the heart-sound signal SH shown in Fig. 8A, with respect to time, frequency, and signal magnitude, by utilizing the wavelet transform, i.e., expression (1). In the contour map, three contour lines represent three integral values, i.e., 10, 20, and 30, respectively.

[0036] The fast Fourier transform transforms a signal (i.e., a two-dimensional signal with respect to time and signal magnitude) that is obtained from each of prescribed time intervals, into a different sort of two-dimensional signal with

respect to frequency and signal magnitude. Therefore, if the function $f(t)$ is subjected to the fast Fourier transform each time the time t is moved from one time interval to the next time interval, the function $f(t)$ is transformed into a three-dimensional signal with respect to time, frequency, and signal magnitude, like the contour map obtained by the wavelet transform.

[0037] The heart-sound-frequency-range determining means 94 determines, based on the three-dimensional graph obtained by the time-frequency analyzing means 92, a frequency range RF of the heart sounds represented by the heart-sound signal SH supplied from the microphone 74, and stores the thus determined heart-sound frequency range RF in the memory device 78. The heart-sound frequency range RF may be one which includes respective frequencies of all heart sounds including first and second heart sounds I, II. However, in the present embodiment, the heart-sound-frequency-range determining means 94 determines a frequency range including frequencies of a second heart sound II as part of the heart sounds. For example, regarding the three-dimensional graph shown in Fig. 8B, the heart-sound-frequency-range determining means 94 determines, as the heart-sound frequency range RF, a range of frequencies which correspond to respective times when the second heart sound II, shown in Fig. 8A, occur, and which correspond to respective signal magnitudes not smaller than a reference value (e.g., 20). Fig. 8B shows the thus determined heart-sound frequency range RF. This heart-sound frequency range RF is characteristic of the subject.

[0038] The reference-waveform determining means 96 extracts, from a portion of the heart-sound signal SH that was detected in a prescribed time interval, a signal component having the frequencies of the heart-sound frequency range RF determined by the heart-sound-frequency-range determining means 94, and determines a waveform of the thus extracted component, as a reference waveform. In addition, the reference-waveform determining means 96 determines a prescribed periodic point on the thus determined reference waveform, as a reference point, and stores the thus determined reference waveform and point in the memory device 78. The reference waveform is also characteristic of the subject. The above-indicated time interval is so prescribed as to include a time or a time interval which is necessary for making a diagnosis. Since, in the present apparatus 10, a pulse-wave-propagation-velocity determining means 110, described later, needs a starting point of a second heart sound II, the prescribed time interval includes the starting point of second heart sound II, and the prescribed periodic point means the starting point of second heart sound II.

[0039] A small-cuff-pressure control means 98 controls, based on the second pressure signal SP_2 supplied from the pressure sensor 52, the pressure control valve 54 and the air pump 56 to increase the air pressure PK_2 in the small cuff 20 up to a prescribed target pressure PM_2 and then keep the pressure PK_2 at the target pressure PM_2 . The target pressure PM_2 is prescribed at such a value which assures that the press surface 30 which is provided on the inner surface of the cuff 12 and to

which the pressure-pulse-wave sensors 28 are fixed, is pressed against the upper arm 14, but does not occlude the flow of blood through a brachial artery 100 of the upper arm 14.

[0040] An optimum-element selecting means 102 selects, from the sixty pressure-sensing semiconductor elements 32 of the four pressure-pulse-wave sensors 28, an optimum pressure-sensing element 32 that is the most appropriate to detect heart sounds (hereinafter, referred to as the optimum element A). Fig. 9 is a cross-section view showing the state in which the cuff 12 is wound around the upper arm 14. As shown in Fig. 9, the pressure-sensing elements 32 provided on the press surfaces 30 of the pressure-pulse-wave sensors 28 have respective different distances from the brachial artery 100 of the upper arm 14. Therefore, it is desirable that one of the pressure-sensing elements 32 that is located right above, or in the vicinity of, the brachial artery 100 be selected as the optimum element A that can detect, with the highest sensitivity, the pressure pulse wave. Fig. 10 shows a relationship between the pressure-sensing elements 32 and respective amplitudes of the pressure-pulse-wave signals SM detected by the elements 32. In the figure, the sequential numbers of the pressure-sensing elements 32 start with one of opposite ends of the array of elements 32 provided on the press surfaces 30. Respective amplitudes of pressure-pulse-wave signals SM detected by nearer pressure-sensing elements 32 to the brachial artery 100 are greater than those detected by remoter elements 32 from the artery 100. Therefore, the optimum-element selecting means 102 selects, as the optimum

element A, one of the pressure-sensing elements 32 that provides a pressure-pulse-wave signal SM having a greater amplitude in the relationship shown in Fig. 10, most preferably, the element 32 that provides the signal SM having the greatest amplitude.

[0041] A filtering means 104 as a first heart-sound determining means subjects the pressure-pulse-wave signal SM supplied from the optimum element A, to a digital filter which allows, based on the heart-sound frequency range RF stored in the memory device 78, only a signal component having frequencies falling in the frequency range RF to pass therethrough. Thus, the filtering means 104 extracts, from the pressure-pulse-wave signal SM, only the signal component having the frequencies falling in the frequency range of the second heart sound II whose level is considerably low in the signal SM.

[0042] A second heart-sound determining means 106 determines a time interval in which a waveform of the signal component extracted by the filtering means 104 best approximates the reference waveform stored in the memory device 78. Since the reference waveform is determined based on the second heart sound II, a portion of the pressure-pulse-wave signal SM that occurs in the time interval determined by the second heart-sound determining means 106 corresponds to the second heart sound II. In addition, in a state in which the waveform of the signal component extracted by the filtering means 104 best approximates the reference waveform, the second heart-sound determining means 106 determines a time point

corresponding to the starting point of the second heart sound II as the reference waveform. This time point indicates a time when the starting point of second heart sound II contained in the pressure-pulse-wave signal SM occurs. The method in which the second heart-sound determining means 106 determines the time interval in which the waveform of the signal component extracted by the filtering means 104 best approximates the reference waveform, may be to obtain a cross-correlation function with respect to the waveform of the signal component extracted by the filtering means 104 and the reference waveform and determine, as the above-indicated time interval, a time interval corresponding to the reference waveform in a state in which the cross-correlation function takes a maximal value.

[0043] A noise removing means 108 subjects the pressure-pulse-wave signal SM supplied from the optimum element A, to a digital filter, and thereby removes noise from the signal SM, so as to extract the pressure pulse wave BAP produced when the brachial artery 100 pulsates. Since the pressure pulse wave BAP is a heartbeat-synchronous wave, the noise removing means 108 removes, from the signal SM, a component having frequencies not lower than 50 Hz. Fig. 11 shows a pressure pulse wave BAP which is freed of noise by the noise removing means 108.

[0044] The pulse-wave-propagation-velocity determining means 110 determines a timing when the rising point of second heart sound II determined by the second heart-sound determining means 106 is detected, a timing when a notch of the pressure pulse wave BAP that corresponds to the second heart

sound II is detected, and determines a time difference between the two timings. The pressure pulse wave BAP has been freed of noise by the noise removing means 108. The thus determined time difference is determined as a pulse-wave propagation time DT (sec) that is needed for the pressure pulse wave BAP to propagate from the aortic valve of the heart to a portion of the brachial artery 100 that is located right below the pressure-pulse-wave sensors 28. The pulse-wave-propagation-velocity determining means 110 determines, based on the thus determined pulse-wave propagation time DT, a pulse-wave propagation velocity PWV (m/sec), according to the following expression (2), pre-stored in the ROM 76:

$$PWV = L/DT \quad \dots (2)$$

The thus determined pulse-wave propagation velocity PWV is displayed on the display device 86. In the above expression (1), L is a length of an artery from an initial end of the aorta to a portion thereof located right below the optimum element A, and is obtained in advance by experiments.

[0045] Figs. 12 and 13 are flow charts representing respective control programs according to which the control device 46 is operated. The flow chart of Fig. 12 represents a heart-sound-characteristic-information obtaining routine, and the flow chart of Fig. 13 represents a pulse-wave-propagation-velocity determining routine.

[0046] First, there will be described the heart-sound-

characteristic-information obtaining routine shown in Fig. 12. This routine is carried out before the routine shown in Fig. 13 is carried out. When the routine of Fig. 12 is carried out, it is needed to wear the heart-sound microphone 74 on the chest of a patient, but it is not needed to wear the cuff 12 on the upper arm 14.

[0047] First, at Step SA1 (hereinafter, "Step" is omitted), the control device 46 resets a number counted by a timer t , to zero. Next, at SA2, the control device 46 reads in the heart-sound signal SH supplied from the heart-sound microphone 74. At SA3, the control device 46 adds one to the number counted by the timer t and, at SA4, the control device 46 judges whether a time represented by the number counted by the timer t has exceeded a prescribed read-in time T_1 corresponding to an average pulse period, i.e., an inverse of an average pulse rate. While negative judgments are made at SA4, Steps SA2 to SA4 are repeated to continue reading in the heart-sound signal SH. Since the heart-sound signal SH is supplied from the heart-sound microphone 74 worn on the chest, the signal SH has a greater signal-to-noise (S/N) ratio than that of the pressure-pulse-wave signal SM supplied from each pressure-pulse-wave sensor 28 worn on the upper arm 14. The S/N ratio of the signal SM is defined as a ratio of the heart-sound component thereof to the remaining components thereof as noise.

[0048] Meanwhile, if a positive judgment is made at SA4, the control proceeds with Steps SA5 and SA6 corresponding to the heart-sound-characteristic-information obtaining means 90.

At SA5, the control device 46 determines, based on the heart-sound signal SH read in while Steps SA2 to SA4 are repeated, a starting point and an ending point of a second heart sound II, using a known technique (so-called "smoothing energy curve") which is widely employed to determine characteristic points of heart sounds. The respective positions of the starting and ending points and the respective times of detection of the starting and ending points are stored in the memory device 78.

[0049] Next, the control goes to SA6 corresponding to the time-frequency analyzing means 92. At SA6, the heart-sound signal SH read in while Steps SA2 to SA4 are repeated is subjected to the wavelet transform. Thus, a time-frequency analyzed signal is obtained as a contour map as shown in Fig. 8B.

[0050] Then, the control goes to SA7 corresponding to the heart-sound-frequency-range determining means 94. At SA7, the control device 46 determines, as a heart-sound frequency range RF characteristic of a second heart sound II of the subject, a range of respective frequencies which correspond to respective times between the starting and ending points, determined at SA5, on the time-frequency analyzed signal, obtained at SA6, and which correspond to respective signal magnitudes not smaller than a reference value. The thus determined heart-sound frequency range RF is stored in the memory device 78.

[0051] Next, the control goes to SA8 corresponding to the reference-waveform determining means 96. At SA8, the control device 46 extracts, from a portion of the heart-sound signal SH,

obtained at Steps SA2 to SA4, that occurs between the starting and ending points of the second heart sound II, determined at SA5, a signal component having the frequencies of the heart-sound frequency range RF determined at SA7, and determines a waveform of the thus extracted component, as a reference waveform. This reference waveform is stored in the memory device 78. Though the heart-sound signal SH read in at SA2 has a considerably great S/N ratio, the signal component extracted at SA2 is obtained by removing noise from the portion of the signal SH that occurs between the starting and ending points of second heart sound II.

[0052] Next, there will be described the pulse-wave-propagation-velocity determining routine shown in Fig. 13. This routine is carried out in a state in which the upper arm 14 is not pressed by the large cuff 18.

[0053] In Fig. 13, first, at Step SB1 corresponding to the small-cuff-pressure control means 98, the control device 46 starts the air pump 56 and operates the pressure control valve 54, so that the pressing pressure P_{K2} of the small cuff 20 is kept at a considerably low pressure of, e.g., 40 mmHg.

[0054] Next, at SB2, a number counted by a timer t is replaced with "0", so that the timer t is reset to zero and, at SB3, the control device 46 outputs the switch signal SC to switch the multiplexer 60 and the EPROM 64 at a period sufficiently shorter than an average pulse period. Then, at SB4, the control device 46 reads in the pressure-pulse-wave signal SM supplied from the multiplexer 60.

[0055] Next, at SB5, the control device 46 adds one to the number counted by the timer t and, at SB6, the control device 46 judges whether a time indicated by the number counted by the timer t has exceeded a prescribed read-in period T_2 . Like the read-in time T_1 , the read-in period T_2 may be equal to an average pulse period, i.e., a length of one average heartbeat-synchronous pulse. Each time one switch signal SC is supplied to the multiplexer 60 at SB3, one of the respective pressure-pulse-wave signals SM detected by the sixty pressure-sensing elements 32 is supplied from the multiplexer 60 to the control device 46. While Steps SB3 to SB6 are repeated sixty times, all the signals SM detected by the sixty elements 32 are supplied from the multiplexer 60 to the control device 46.

[0056] Next, the control goes to SB7 and SB8 corresponding to the optimum-element selecting means 102. First, at SB7, the control device 46 determines respective amplitudes of the respective pressure-pulse-wave signals SM which have been read in while Steps SB3 to S6 are repeated. At SB8, the control device 46 determines the greatest one of the respective amplitudes determined at SB7, and determines, as the optimum element A, one of the pressure-sensing elements 32 that provides the greatest amplitude.

[0057] Next, the control goes to SB9 corresponding to the filtering means 104. At SB9, the control device 46 extracts, from the pressure-pulse-wave signal SM supplied from the optimum element A selected at SB8, a signal component having frequencies falling in the heart-sound frequency range RF stored

at SA7 in Fig. 12. The signal component extracted from the pressure-pulse-wave signal SM has the frequencies of the second heart sound II of the subject.

[0058] Subsequently, the control goes to Steps SB10 and SB11 corresponding to the second heart-sound determining means 106. At SB10, the control device 46 determines a cross-correlation function with respect to the waveform of the signal component extracted at SB9 and the reference waveform stored at SA8 in Fig. 12. At SB11, the control device 46 determines a position of the reference waveform relative to the waveform extracted at SB9, in a state in which the cross-correlation function takes a maximal value, and determines, as a time of occurrence of a starting point of the second heart sound II as the extracted waveform, a time corresponding to a position of the starting point of the second heart sound II on the extracted waveform that corresponds to the starting point of the second heart sound II determined and stored at SA5 in Fig. 12.

[0059] Next, the control goes to SB12 corresponding to the noise removing means 108. More specifically described, at S8, the control device 46 subjects the pressure-pulse-wave signal SM detected by the optimum element A, to a digital filter, so as to remove a signal component having frequencies not lower than 50 Hz. Thus, the pressure pulse wave BAP is extracted from the pressure-pulse-wave signal SM. Next, at SB13, the control device 46 determines, based on the pressure pulse wave BAP extracted at SB12, a time of occurrence of a notch (Fig. 11) to the pressure pulse wave BAP that corresponds to the starting point of second

heart sound II.

[0060] Then, the control goes to Steps SB14, SB15 and SB16 corresponding to the pulse-wave-propagation-velocity determining means 110. At SB14, the control device 46 determines a pulse-wave propagation time DT between the time of occurrence of the starting point of the second heart sound II determined at SB11 and the time of occurrence of the notch of the pressure pulse wave BAP determined at SB13. Next, at SB15, the control device 46 determines a pulse-wave propagation velocity PWV by replacing the parameter DT of the expression (2) with the time difference DT determined at SB14. Next, at SB16, the thus determined pulse-wave propagation velocity PWV is displayed on the display device 86.

[0061] In the illustrated embodiment, the memory device 78 stores the two pieces of heart-sound characteristic information which is characteristic of the heart-sound signal SH of the living subject, i.e., the heart-sound frequency range RF and the reference waveform and, at Steps SB10 and SB11 (the second heart-sound determining means 106), the starting point of the second heart sound II is determined, based on the reference waveform characteristic of the subject, on the pressure-pulse-wave signal SM supplied from the pressure-pulse-wave sensor 28. Thus, even if the magnitude of the heart-sound component is weak relative to that of the signal SM as a whole, the starting point of second heart sound II can be determined with accuracy.

[0062] More specifically described, in the illustrated embodiment, the heart-sound frequency range RF characteristic

of the subject, determined based on the heart-sound signal SH obtained in advance from the chest of the subject, is stored in the memory device 78 at SA7; and the component having the frequencies falling in the heart-sound frequency range RF is extracted from the pressure-pulse-wave signal SM supplied from the pressure-pulse-wave sensor 28, at SB9 (the filtering means, i.e., the first heart-sound determining means 104). Since the reference waveform stored in the memory device 78, i.e., the second-heart-sound-II component from its starting point to its ending point is one which has been measured from the chest of the subject, the component has a great S/N ratio. Yet, the component is characteristic of the subject. Moreover, at Steps SB10 and SB11 (the second heart-sound determining means 106), a waveform of a portion of the signal extracted at SB9 that best approximates the reference waveform is determined as the second heart sound II. Thus, an accurate heart-sound signal can be obtained from the pressure-pulse-wave signal SM.

[0063] While the present invention has been described in its preferred embodiment by reference to the drawings, it is to be understood that the invention may otherwise be embodied.

[0064] For example, in the illustrated apparatus 10, the memory device 78 stores the heart-sound characteristic information which is obtained from the heart-sound signal SH produced by the heart-sound microphone 74. However, in the case where the memory device 78 is externally accessible to delete the information stored therein and store new information therein, it is possible to employ a separate device which measures a heart

sound of a living subject and obtains heart-sound characteristic information from the measured heart sound, and store the thus obtained heart-sound characteristic information in the memory device 78. In the latter case, the apparatus 10 may not employ the heart-sound microphone 74.

[0065] In addition, in the illustrated apparatus 10, the heart-sound signal SH is subjected to the time-frequency analysis, and the thus obtained time-frequency-analyzed signal is used to determine the heart-sound frequency range RF and the reference waveform. The filtering means (the first heart-sound determining means) 104 extracts, from the pressure-pulse-wave signal SM, the component having the frequencies falling in the heart-sound frequency range RF, and the second heart-sound determining means 106 determines, as a second heart sound II, a portion of the extracted signal that best approximates the reference waveform. However, either one of the first and second heart-sound determining means 104, 106 can be omitted. More specifically described, since the component that is extracted from the pressure-pulse-wave signal SM and has the frequencies falling in the heart-sound frequency range RF is a sort of heart-sound signal extracted from a physical signal, the second means 106 may be omitted. Alternatively, the filtering means 104 may not be employed to extract, from the pressure-pulse-wave signal SM, the component having the frequencies falling in the heart-sound frequency range RF, and the second means 106 may be adapted to directly compare the pressure-pulse-wave signal SM with the reference waveform and determine, as a second

heart sound II, a portion of the signal SM that best approximates the reference waveform.

[0066] It is to be understood that the present invention may be embodied with other changes, improvements and modifications that may occur to a person skilled in the art without departing from the spirit and scope of the invention defined in the appended claims.